

Handle decompositions

4-12-18

$\sigma \leq k \leq n$ ← n is the dim. k is called the index of the handle

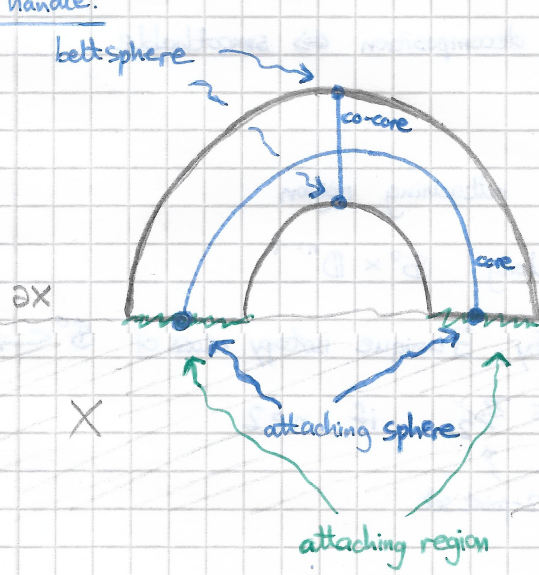
4-manifolds

$D^k \times D^{n-k}$ n -dimensional k -handle ("thickened k -cell")

Lecture

Anatomy of a handle:

Picture is of a
2-dimensional
1-handle:
 $D^1 \times D^1$



- $D^k \times \{0\}$ core
- $\{0\} \times D^{n-k}$ cocore
- $\partial D^k \times D^{n-k}$ attaching region
- $\partial D^k \times \{0\}$ attaching sphere
- $\{0\} \times \partial D^{n-k}$ belt sphere

Handles attached using attaching maps

$$\varphi: \partial D^k \times D^{n-k} \longrightarrow \partial X$$

(smooth) embedding

HW1: Isotopy of φ does not affect diffeomorphism type of

where X is an n -manifold.

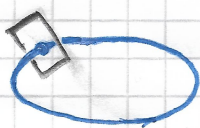
$$X \cup_{\varphi} h$$

Then $X \cup_{\varphi} (D^k \times D^{n-k})$ is specified by

an (i) embedding $S^{k-1} \hookrightarrow \partial X$ (i.e. a knot in ∂X)

and a (ii) trivialization of its trivial normal bundle (i.e. a framing)

Ex. Suppose $k=2$



Fix some reference framing f_0

then any other framing corresponds to an element

$$\text{of } \pi_{k-1}(O(n-k))$$

$$\cong \text{Gram-Schmidt } GL(n-k)$$

Always: "Smooth the corners" so that $X \cup_{\varphi} h$ is a smooth n -manifold

Given a compact manifold X , $\partial X = \partial_- X \amalg \partial_+ X$, a handle decomposition

of $(X, \partial_- X)$ is an identification of X with $(\partial_- X \times \mathbb{I}) \cup \{\text{handles}\}$

Fact: Any smooth, compact manifold pair $(X, \partial_- X)$ has a relative handle decomposition.

Aside: Any topological n -mfd. pair has a topological handle decomposition, except when $n=4$!

References: $n=3$ Moise, $n \geq 6$ Kirby-Siebenmann, $n=5$ Freedman-Quinn

A 4-manifold has a topological handle decomposition \Leftrightarrow smoothable

0-handles: $D^0 \times D^n$ has empty attaching region

1-handles: $D^1 \times D^{n-1}$ attached along $S^0 \times D^{n-1}$

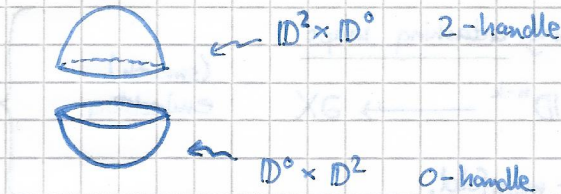
(compact)
 -) if ∂X connected, nonempty, \exists unique isotopy class of $S^0 \hookrightarrow \partial X$

-) framings $\pi_0(O(n-1)) \cong \mathbb{Z}/2$ if $n \geq 2$
 2-point set

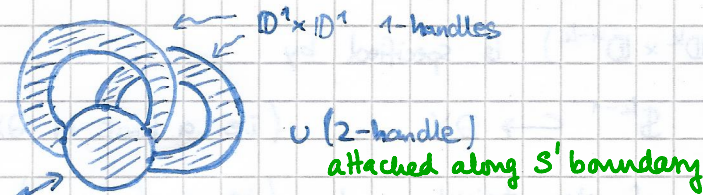
framing determines whether resulting manifold orientable.
 i.e. if result orientable, \exists unique choice of framing

Ex.: Surfaces

-) Sphere S^2 :

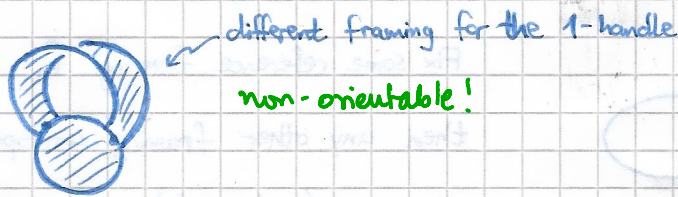


-) Torus:

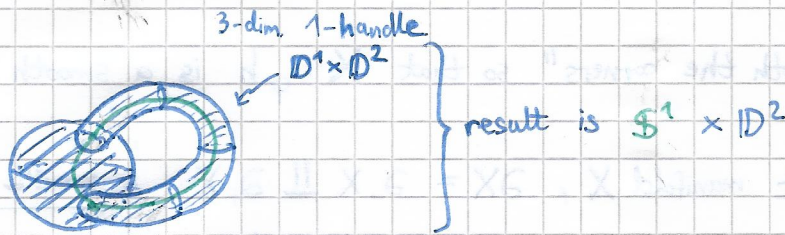


0-handle $D^0 \times D^2$

-) Mobius band



Ex.: 3-manifolds



(n-1)- and n-handles have unique framings:

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for $n \neq 2$

4-manifolds

Lecture

$$k = n-1, \pi_{n-2}(\overset{=S^0}{O(1)}) = \sigma \text{ if } n \neq 2$$

$$k = n, \pi_{n-1}(O(\sigma)) = \sigma$$

Note: n-handles attached along $\partial D^n = S^{n-1}$

For $n \leq 4$, any self-diffeo. of S^{n-1} is isotopic to either identity or reflection.

→ Exotic spheres in higher dim.

⇒ \exists unique way to attach an n-handle to S^{n-1} for $n \leq 4$

2-handles:

$$\text{framings: } \pi_1(O(n-2)) \cong \begin{cases} 0 & n \leq 3 \\ \mathbb{Z} & n = 4 \\ \mathbb{Z}/2 & n \geq 5 \end{cases}$$

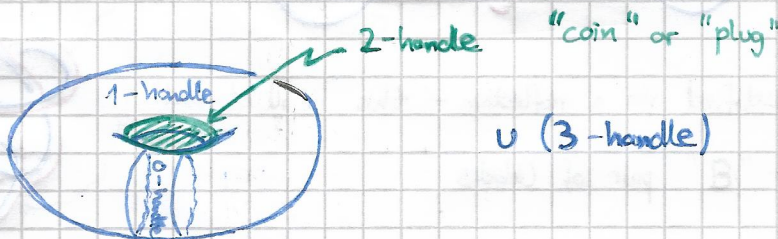
In particular: D^2 -bundles over S^2 correspond to integers \mathbb{Z}

"clutching function"

$$S^1 \rightarrow O(2)$$

↑
equator of S^2

Ex: S^3



Turning handles upside down: Given a (relative) handle decomposition for $(X^n, \partial_- X)$ we can produce one for $(X, \partial_+ X)$ bar denotes opposite orientation

Every k-handle in $(X, \partial_- X)$ becomes an $(n-k)$ -handle in $(X, \partial_+ X)$

Fact (HW 1^b): If X is connected, we can assume it has a single σ -handle (if $\partial_- X = \emptyset$) or no σ -handle (if $\partial_- X \neq \emptyset$)

3-manifold topologists
Some people call H_m a handlebody

3-manifolds (closed, orientable)

$$\{ \sigma\text{-handle} \} \cup \{ m \text{ 1-handles} \} \cup \{ k \text{ 2-handles} \} \cup \{ 3\text{-handle} \}$$

$$H_m := \mathbb{Z}^m S^1 \times D^2$$

$$\mathbb{Z}^k S^1 \times D^2$$

Boundary connected sum \natural :

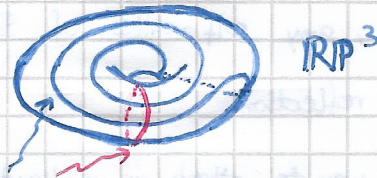
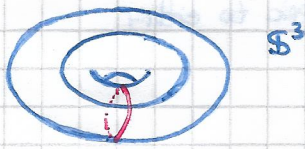


Since 3-mfld. is closed $\Rightarrow k=m$

Any 3-manifold is the union of 2 copies of H_m for some m .
closed, orientable

This is called a Heegaard decomposition.

The 3-manifolds obtained from $S^1 \times D^2 \cup S^1 \times D^2$ } Genus 1 Heegaard splitting
 are called the Lens spaces.

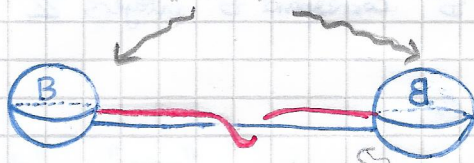


2-handles attached along these curves
 In the case that the boundary is S^2 , the 3-handle attaches uniquely

4-manifolds (Kirby diagrams)

σ -handle has boundary $S^3 = \mathbb{R}^3 \cup \{\infty\}$

the two feet of a 1-handle



blue: attaching spheres of 2-handles

red curves specifies framing of 2-handles



⚠ Have to be careful when they are running over a 1-handle \rightarrow belt trick

The two balls are identified via a reflection - this is illustrated by the "B" - "B" pair of labels

If 4-mfld. is closed, oriented

$$\{3\text{- and }4\text{-handles}\} \cong \#^m S^1 \times D^3$$

so has boundary $\#^m S^1 \times S^2$

Laudenbach-Poenaru: Any diffeomorphism of $\#^m S^1 \times S^2$ extends over $\#^m S^1 \times D^3$

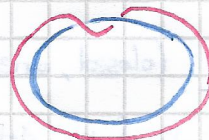
Upshot: If X closed, no need to specify (draw) the 3- and 4-handles.

Ex.:



If we want this to represent a closed mfd., have to add $\{3\text{-handle}\} \cup \{4\text{-handle}\}$ (which we do not draw)

$$\rightsquigarrow S^1 \times S^3$$



$\rightsquigarrow CP^2$ if we add a 4-handle

References for now:

[Gompf, Stipsicz: 4-manifolds and Kirby Calculus]

[Kirby: The topology of 4-manifolds]

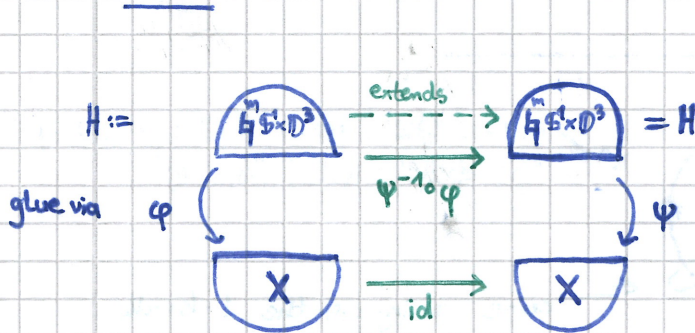
[Scorpan: The wild world of 4-manifolds] * read with caution - this book contains a lot of context, references, and intuition, but not always all the detail. Sometimes misleading

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4-mflds.
Lecture

Clarification:

Laudenbach - Poenaru: Any self-diffeomorphism of $\#^m S^1 \times S^2$ extends to a self-diffeomorphism of $\#^m S^1 \times D^3$.

Motto: "3- and 4-handles don't need to be drawn (in a diagram for a closed 4-mfld.)"



Precisely: $X \cup_{\phi} H \cong X \cup_{\psi} H$ for all gluings ϕ, ψ

Need: $F: X \cup_{\phi} H \rightarrow X \cup_{\psi} H$

Define $F|_X := id$

$$F|_{\partial H} := \psi^{-1} \circ id \circ \phi: \partial H \rightarrow \partial H$$

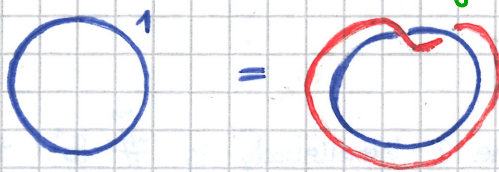
" $\#^m S^1 \times S^2$ "

they agree on the overlap

Framings: (2-handles in a 4-manifold)

Fix a reference framing.

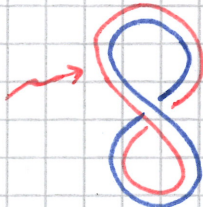
Framings correspond to $\pi_1(O(2)) \cong \mathbb{Z}$
"linking number framing"



don't need to specify orientations if we require blue & red to be oriented in the same direction: flipping both orientations does not change Linking numbers

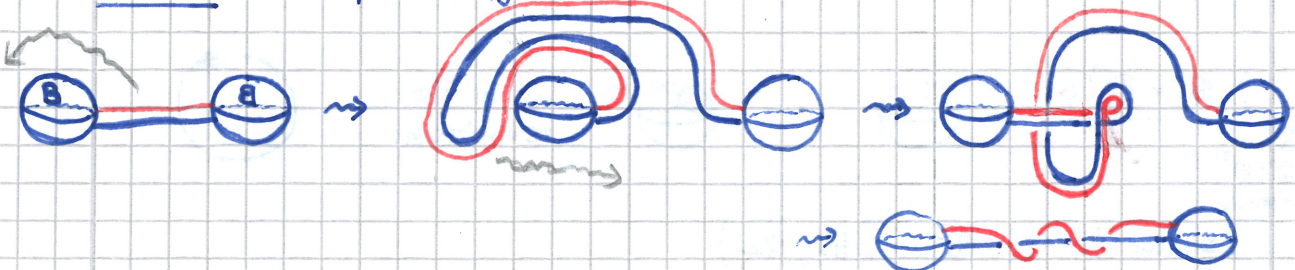
"blackboard framing":

take pushoff on the blackboard



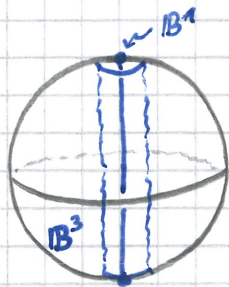
But this is not preserved under isotopies in S^3 .

Problem: Not always working in S^3



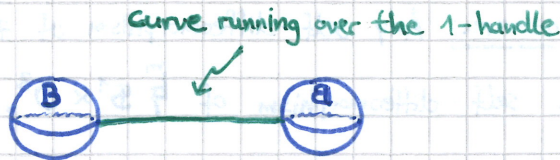
New notation for 1-handles:

"A bridge is the same as an underpass"

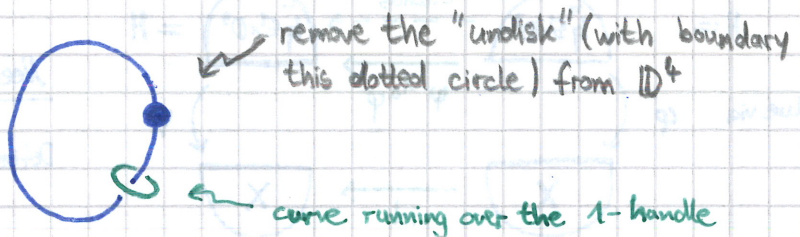


$$\mathbb{I} \times (\mathbb{B}^3 \setminus \nu \mathbb{B}^1) \cong \mathbb{I} \times (\mathbb{S}^1 \times \mathbb{D}^2) \\ \cong \mathbb{S}^1 \times \mathbb{D}^3$$

Old notation:



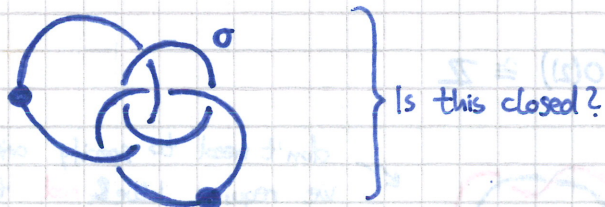
New notation:



Any (closed, smooth, oriented) 4-manifold can be represented by a link in \mathbb{S}^3 decorated with dots and integers.

- "dotted" components must form an unlink

Rmk: The dot is there so that we do not confuse 1- and 2-handles

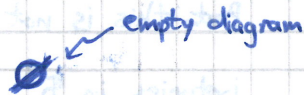


& such that the boundary of the 2-handlebody is $\#^m \mathbb{S}^1 \times \mathbb{S}^2$ for some $m \geq 0$.

don't need this if manifold has boundary.

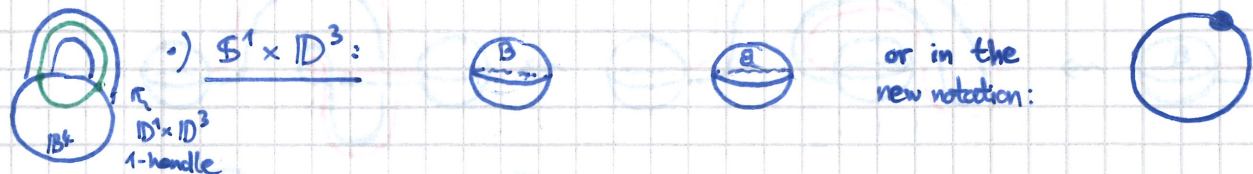
Examples:

.) \mathbb{S}^4 :



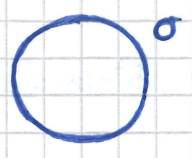
has a 0-handle and a 4-handle

Schematic:

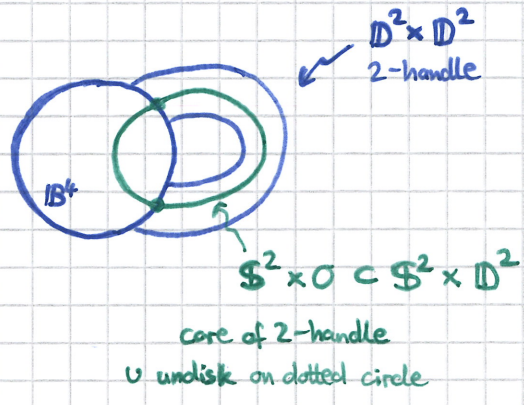


-2- Similar for $\mathbb{S}^1 \times \mathbb{S}^3$ (HW, 2c)

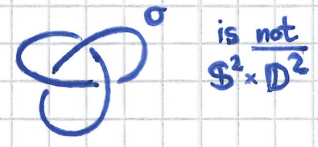
.) $S^2 \times D^2$:



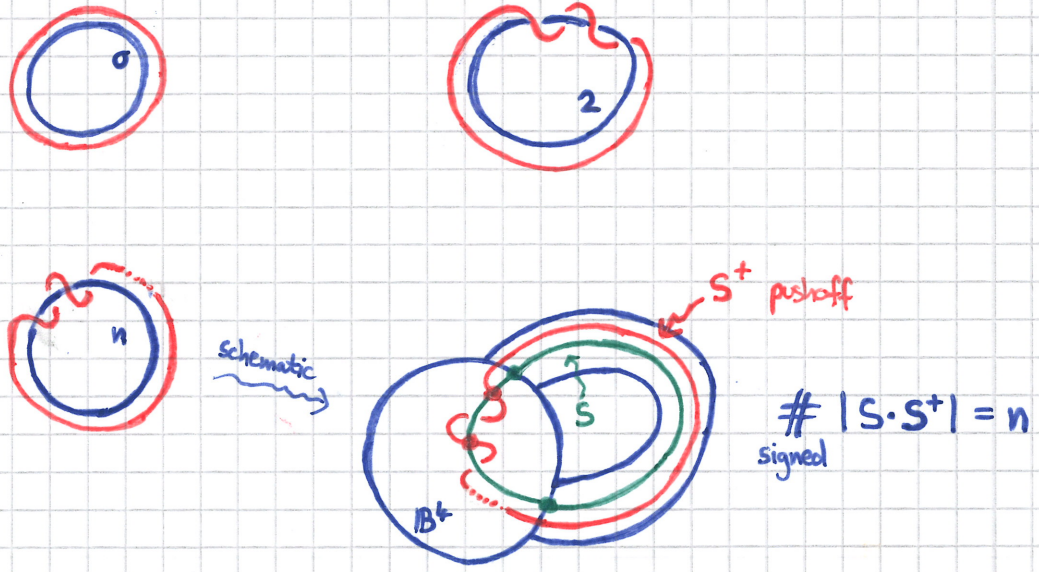
Schematic:



Note:



Remark:

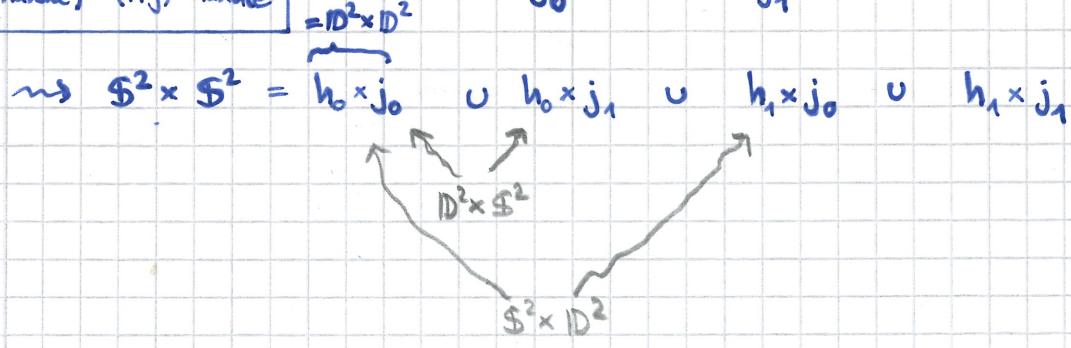


.) $S^2 \times S^2$:

$S^2 = \{\sigma\text{-handle}\} \cup \{2\text{-handle}\}$

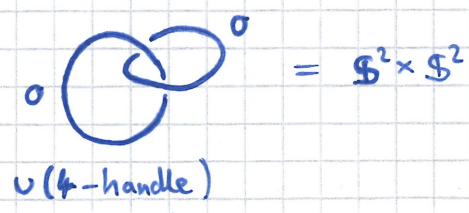
first S^2 : h_0 h_1
 second S^2 : j_0 j_1

$(i\text{-handle}) \times (j\text{-handle}) = (ij)\text{-handle}$



2-handles are attached along $S^1 \times \sigma$ and $\sigma \times S^1$

Namely, along the Hopf Link
 (recall from previous lectures)





$$= \mathbb{S}^2 \tilde{\times} \mathbb{S}^2$$

twisted \mathbb{S}^2 -bundle over \mathbb{S}^2

(will discuss why in future class)